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when the proper
acceleration is $3g$ to the
left. Find the
sensitivity a and bias b .

What is the dynamic

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range (in decibels) of this
accelerometer?

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Suppose that the
machine of Exercise 8 of
Chapter 4 is composed
in a synchronous side-by-

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side composition with
the following machine:
Find a tight lower
bound on the time
between events a and b .

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programmable thermostat allows you to select 4 times, $0 \leq T_1$

$\cdot \cdot \cdot T_4 < 24$ (for a 24-hour cycle) and the corresponding setpoint temperatures $a_1, \cdot \cdot \cdot, a_4$.

4. Construct a timed automaton that sends the event `aito` to the heating systems controller.

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input event that occurs
less than 80 ms after the
previous ...

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books out there that cover some interesting ways of looking at the topic area. One of them that I like has the wonderful advantage of being free: E. A. Lee and S. A. Seshia, Introduction to Embedded Systems - A Cyber-Physical Systems Approach, LeeSeshia.org, 2017.

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Berkeley: 3 Warning
(adapted from CS 161)
This lecture may discuss
vulnerabilities in
embedded systems. This
is notintended as an
invitation to go exploit
those vulnerabilities.

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Consider The

Deterministic Finite-
state Machine In Figure
3.14 That Models A
Simple Traffic Light: 74
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DYNAMICS Input:
Tick: Pure Output: Go,

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Stop: Pure Green Tick /
Go Red Tick / Stop
Tick / Stop Yellow
Figure 3.14:

Deterministic Finite-
state Machine For
Exercise 5 (a) Formally
Write ...

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bbd8c479cd625e27cfd2

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