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L1 Adaptive Control Theory | Guide books

1 Adaptive Control Theory: Guaranteed Robustness with Fast Adaptation Speyer, Jason L., and Jacobson, David H., Primer on Optimal Control Theory Betts, John T., Practical Methods for Optimal Control and Estimation Using Nonlinear Programming, Second

L1 Adaptive Control Theory

The book L1 Adaptive Control Theory: Guaranteed Robustness with Fast Adaptation, by Naira Hovakimyan and Chengyu Cao, describes a new method known as L1 adaptive control for bringing linear system design methods into adaptive control to confront several open problems, including the selection and tuning of adaptation gains, guaranteed transient performance of both states and controls, and guaranteed robustness margins.

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