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Title: VE 650 BARRIER Author: alberto.borinato Created Date: 2/20/2012 10:20:02 AM

VE 650 BARRIER - IMCCK

VE.650 – Barrier only – 24v Intensive duty 6.5m barrier. VE.650A2 – 2 Piece 6.5m barrier boom (includes joining piece) VE.C650 – 6.5m 90mm circular barrier boom VE.AM – Swinging tip rest VE.RAST – 2m of barrier skirt VE.AF – Fixed tip rest. VE.L650 – Light kit for 6.5m barrier boom VE.CAT650 – Reflective stickers for VE.650 barrier boom. Kit codes

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VE.650 is also ready for operations in case of power failure through the battery pack. Furthermore, thanks to the innovative conceal system, you can install the FTC.S ensuring maximum security and perfect integration.

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This monograph is the first large-scale corpus analysis of French *il y a* clefts. While most research on clefts focusses on the English ‘ prototypical ’ *it*-cleft and its equivalents across languages, this study examines the lesser-known *il y a* clefts – of both presentational-eventive and specificational type – and provides an in-depth analysis of their syntactic, semantic and discourse-functional properties. In addition to an extensive literature review and a comparison with Italian *c’ è* clefts and with French *c’ est* clefts, the strength of the study lies in the critical approach it develops to the common definition of clefts. Several commonly used criteria for clefts are applied to the corpus data, revealing that these criteria often lead to ambiguous results. The reasons for this ambiguity are explored, thus leading to a better understanding of what constitutes a cleft. In this sense, the analysis will be of interest to specialists of

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Romance and non-Romance clefts alike.

Deixis is a field of research that has generated increased interest among linguists. This volume provides an overview of deixis, focusing on Romance languages but also reaching beyond this perspective. The editors and authors hope that readers, regardless of their familiarity with Romance languages, will gain new insights into deixis in general, and into the similarities and differences between deictic structures among the languages of the world.

The concern for the fast-disappearing language stocks of the world has arisen particularly in the past decade, as a result of the impact of globalization. This book appears as an answer to a felt need: to catalogue and describe those languages, making up the vast majority of the world's six thousand or more distinct tongues, which are in danger of disappearing within the next few decades. Endangerment is a complex issue, and the reasons why so many of the world's smaller, less empowered languages are not being passed on to future generations today are discussed in the book's introduction. The introduction is followed by regional sections, each authored by a notable specialist, combining to provide a comprehensive listing of every language which, by the criteria of endangerment set out in the introduction, is likely to disappear within the next few decades. These languages make up ninety per cent of the world's remaining language stocks. Each regional section comprises an introduction that deals with problems of language preservation peculiar to the area, surveys of known extinct languages, and problems of classification. The introduction is followed by a list of all known languages within the region,

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endangered or not, arranged by genetic affiliation, with endangered and extinct languages marked. This listing is followed by entries in alphabetical order covering each language listed as endangered. Useful maps are provided to pinpoint the more complex clusters of smaller languages in every region of the world. The Encyclopedia therefore provides in a single resource: expert analysis of the current language policy situation in every multilingual country and on every continent, detailed descriptions of little-known languages from all over the world, and clear alphabetical entries, region by region, of all the world's languages currently thought to be in danger of extinction. The Encyclopedia of the World ' s Endangered Languages will be a necessary addition to all academic linguistics collections and will be a useful resource for a range of readers with an interest in development studies, cultural heritage and international affairs.

This book presents a hypothesis-based description of the clausal structure of German Sign Language (DGS). The structure of the book is based on the three clausal layers CP, IP/TP, and VoiceP. The main hypothesis is that scopal height is expressed iconically in sign languages: the higher the scope of an operator, the higher the articulator used for its expression. The book was written with two audiences in mind: On the one hand it addresses linguists interested in sign languages and on the other hand it addresses cartographers.

This book showcases the state of the art in the corpus-based linguistics of medieval Celtic languages. Its chapters detail theoretical advances in analysing variation/change in the Celtic languages and computational tools necessary to process/analyse the data. Many contributions situate the Celtic material in the broader field of corpus-based diachronic linguistics. The application of computational

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methods to Celtic languages is in its infancy and this book is a first in medieval Celtic Studies, which has mainly concentrated on philological endeavours such as editorial and literary work. The Celtic languages represent a new frontier in the development of NLP tools because they pose special challenges, like complicated inflectional morphology with non-straightforward mappings between lemmata and attested forms, irregular orthography, and consonant mutations. With so much data available in non-electronic form and ongoing efforts to convert these data to computer-readable format, there is much room for the developing/testing of new tools. This book provides an overview of this process at a crucial time in the development of the field and aims to make the data accessible to computational linguists with an interest in diachronic change.

This book explores the linguistic expression of identity, intended as the social positioning of self and others, by focusing mostly on a scenario of prolonged language contact, namely the ancient Mediterranean area. The volume includes studies on language contact and on identity strategies developed at different levels of analysis, from phonetics to pragmatics, in, among others, Latin, Greek, Coptic, Syriac, (Cypriot) Arabic, Medieval Sardinian.

This book covers the essentials of modality and offers both foundational ideas and cutting edge advances. The book consists of what are essentially tutorials on modality and modal notions, covering definitions of modality, morphosyntactic form, conceptual and logical semantics, historical development, and acquisition. There are also specific chapters on modality in Zapotec and American Sign Language,

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which show the range of forms that modal notions can take. To assist its tutorial function, the book closes with a comprehensive conceptual outline of all the chapters. Key features: new series textbook covers the essentials of modality

Minimally invasive surgery has impacted the outcomes of surgery more than any technology since the development of sterile technique. The hard science has demonstrated that decrease in wound complications and recovery time has created the biggest gap with open approaches to surgery. The total economic benefit may be unfathomable when looked at comprehensively. Integral to the rise of minimal access and therapeutic techniques in surgery has been the growth of technological improvements over time. Beginning with insufflators, videoscopy, and energy devices, that evolution has continued into the development of tele-surgical devices that feature full articulation of instruments, high-resolution 3-D optics, and computer assisted movement. This has come with controversy – as the dominant manufacturer of robotic assisted devices, Intuitive Surgical, and their generations of da Vinci surgical platforms, holds enough market share to spur cries of monopoly and financial excess. However, with over 3000 world-wide systems in use, and over 6000 peer-reviewed research articles, the impact of robotic surgery cannot be ignored. The current state of data suggests equivalency in most procedures with regard to traditional outcome measures, equal or somewhat elevated costs, with specific areas of superiority. The first section of this textbook, Surgical Robots, covers the history, economics, training, and medico-legal aspects of robotic surgery that will be of interest to students, residents, fellows, surgical staff, and administrators or public health specialists who seek to gain a comprehensive background on robotic surgery, or justification for purchasing a robotic system for their institution. Surgeons will also find this background valuable to their practice, to give context to their procedures so they can better

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counsel their patients, help with advocating for robotic platform purchases, and proactively prepare themselves for medico-legal issues. The chapter on legal issues will have specific instances of robotic surgery-related lawsuits and their outcomes, a first for robotic surgery texts. The second section of this textbook, Robotic Procedures, will contain a comprehensive catalogue of procedures that have been performed robotically in general surgery, gynecology, urology, plastic surgery, cardiothoracic, and otolaryngology. Each author will cover the existing literature, preoperative planning, room and patient setup, steps of the procedure, and postoperative care. Standardized room maps and port placement will help the student, resident, fellow, surgeon or OR Staff to quickly reference these before cases. Each chapter will also cover the specific equipment needs and expected complexity of the procedures, allowing administrators to better gauge how to prepare for, or ration, use or their robotic resources. The final section, Future of Robotics, will give the entire scope of audience a look into what exciting advancements in the field are on the horizon. This textbook is a complete resource for robotic-assisted minimally invasive surgery, covering the history, current state, technical and clinical aspects, and future considerations that may be of interest to any who has a role, stake, or curiosity regarding robotic surgery.

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